**/PROG MAIN\_VISPRG**

LINE\_TRACK;

LINE\_TRACK\_SCHEDULE\_NUMBER : 0;

LINE\_TRACK\_BOUNDARY\_NUMBER : 0;

CONTINUE\_TRACK\_AT\_PROG\_END : TRUE;

/MN

1: LBL[1] ;

2: R[55:Counter\_Camera]=30 ;

3: ;

4: LBL[5] ;

5: LBL[2] ;

6: WAIT DI[2:Camera\_Trigger]=ON+ ;

7: VISION RUN\_FIND 'FINDTHEOBJECT\_210178' ;

8: ;

9: VISION GET\_OFFSET 'FINDTHEOBJECT\_210178' VR[1] JMP LBL[5] ;

10: ;

11: PR[R[55]]=VR[1].FOUND\_POS[1] ;

12: ;

13: R[55:Counter\_Camera]=R[55:Counter\_Camera]+1 ;

14: ;

15: IF R[55:Counter\_Camera]>39,JMP LBL[1] ;

16: ;

17: JMP LBL[2] ;

18: ;

/POS

/END